# INTERNATIONAL



## Inclinometer **HIT 1500**

**CAN** interface

**MEMS Technology** 

Motion compensated

Accuracy: 0.1 ° typ.







#### **Features**

- Motion compensated inclination measurement via sensor fusion
- High signal dynamics
- High degree of accuracy
- Temperature compensation
- Diverse signal output
  - Inclination static
  - Motion compensated inclination
  - Acceleration in 3 axes
  - Rotation rate in 3 axes
- E13 approved for road vehicles

#### Description

In many applications, angles of inclination have to be measured to ensure the function of machines and systems and to control processes.

The HIT 1500 measuring systems are single or double axis measuring systems for the detection of the inclination with regards to their horizontal plane. The HIT 1500 family has been especially developed for the detection of the inclination inside of dynamic systems.

The inclination signal is calculated in quasi-static condition, based on a 3 axis acceleration sensor using MEMS technology (Micro-Electro-Mechanical System).

An additional gyroscope is provided for the calculation of the inclination in the dynamic system. A motion compensated inclination signal is calculated by fusioning the two physically independent signals of acceleration and gyro.

In addition to the inclination signals, the acceleration and gyro values are also available in all 3 spatial axes. The application developer is provided with a higher degree of freedom which can be used for the optimisation of control processes in the machine control.

#### **Application fields**

Fields of application are all mobile working machines with requirements especially for dynamic position or inclination detection are used.

Thus, the HIT 1500 provides excellent dynamic characteristics and is therefore particularly suited for the active orientation, stabilisation and control of the inclination in mobile machines such as boom lifts and work platforms, cranes and mobile cranes, construction and drilling devices, agricultural and municipal machines, etc.

Especially for the use in public traffic vehicles, HIT 1500 is approved for road vehicles according ECE type approval.

Sensors for applications with increased functional safety are also available on request.

#### **Technical details**

Input data inclination					
Axes			1/2		
Measuring range (primary a	xis; "longitudinal")	0	±180 (±15 / ±60 / ±120 available)		
Measuring range (secondary; "lateral")		0	±90 (±15 / ±60 available)		
Resolution		0	0.01		
Temperature coefficient (-20 to +60°C)		°/10K	< 0.03 typ. (RMS) 0.06 max.		
Long-term stability		°/1000h	< 0.1 typ. (RMS) 0.15 max.		
Static	Dynamic performance	Hz	2 (-3 dB)	-	
	Accuracy	0	< 0.1 typ. (RMS)	0.2 max.	
	Repeatability	۰	< 0.05 typ. (RMS)	0.1 max.	
Motion compensated	Dynamic performance	Hz	50 (-3 dB)	'	
-	Update rate	Hz	200		
Input data acceleration (A	CC)				
Axes	,		3		
Measurement range		m/s²	±30 in 3 axes		
Resolution		m/s²	0.01		
Cutoff frequency		Hz	50 (-3 dB)		
Accuracy		m/s²	< 0.02 typ. (RMS)	0.04 max.	
Temperature coefficient (-20 to +60°C)		(m/s²)/10K	< 0.005 typ. (RMS)	0.01 max.	
Long-term stability	,		< 0.01 typ. (RMS)	0.02 max.	
Input data gyro (GYRO)		(, 0 ),		0.02	
Axes			3		
Measurement range		°/s	±250 in 3 axes		
Resolution		°/s	0.01		
Cutoff frequency		Hz	50 (-3 dB)		
Accuracy		°/s	< 0.4 typ. (RMS) 1.0 max.		
Temperature coefficient (-20	) to +60°C)	(°/s)/10K	< 0.03 typ. (RMS)	0.1 max.	
Long-term stability	7.60 - 00 - 07	(°/s)/1000h	< 0.05 typ. (RMS)	0.2 max.	
Output data		( 73)/ 100011	- 0.00 typ. (rawo)	U.Z Max.	
Output signal			CANonen protocol or SAE	J1939 protocol, depending on version	
Environmental Conditions			CANOPER PRODUCTION SAL C	11939 protocol, depending on version	
		°C	-20 +60		
Compensated temperature r		°C			
Operating temperature range	e	°C	-40 +85		
Storage temperature range			-40 +85		
Operating Altitude		mNN	0 3000		
C € marked			EN 61000-6-1 / 2 / 3 / 4 (see Declaration of Conformity)		
us marking 1)			UL Certificate number: E318391		
® marked			E13*10R00*10R05*14421*00		
	EN 60068-2-6 at 10 500 Hz		5 g (criteria B)		
Shock resistance acc. to DIN	N EN 60068-2-27		20 g, 11 ms half sine (criteria B)		
Protection type <sup>2)</sup> acc. to DIN EN 60529 acc. to ISO 20653			IP66, IP67, IP69 IP6K9K		
Other data					
Supply voltage when applied acc. to UL specifications		V DC	9 36 - limited energy - according to 9.4 UL 61010; Class 2; UL 1310/1585; LPS UL 60950		
Residual ripple of supply voltage		%	< 5		
Power consumption		W	< 1		
Housing material			Aluminium, anodized		
Weight		g	~400		

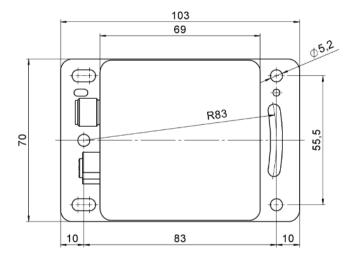
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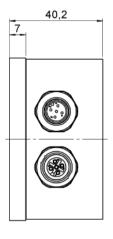
Protocol data for CANopen						
Communication profile	CiA DS 301 V4.2					
NMT-Services	CiA DSP 302 V4.1					
Layer setting services and protocol	CiA DSP 305 V2.2					
Device profile	CiA DS 410 V1.3					
Baud rates	10 kbit 1 Mbit acc. to. CiA DS305 V2.2					
Transmission services - PDO - Transfer	Measured values as a 16 bit value, status synchronous, asynchronous, cyclical					
Node ID / Baud rate	Can be set via Manufacturer Specific Profile & LSS					
Default Settings	Baud rate: 250 kbit/s Node ID: 1					
Protocol data for SAE J1939						
Data Link Layer	SAE J1939-21					
Network Layer	SAE J1939-31					
Network Management	SAE J1939-81					
SSI, SSI2	SAE J1939-DA					
Default Settings	Baud rate: 250 kbit/s CAN data Device address: 1					
Network Layer  Network Management  SSI, SSI2	SAE J1939-31 SAE J1939-81 SAE J1939-DA Baud rate: 250 kbit/s CAN data Device address: 1					

Reverse polarity protection of the supply voltage and overvoltage protection are provided. Note:

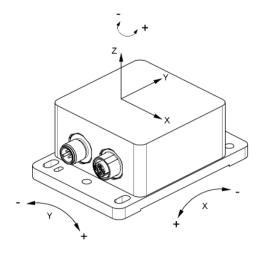
- 1) Environmental conditions according to 1.4.2 UL 61010-1; C22.2 no. 61010-1
- $^{\rm 2)}\mbox{With mating connector of corresponding protection type fitted}$

#### **Dimensions**





### Coordinate system and turning direction



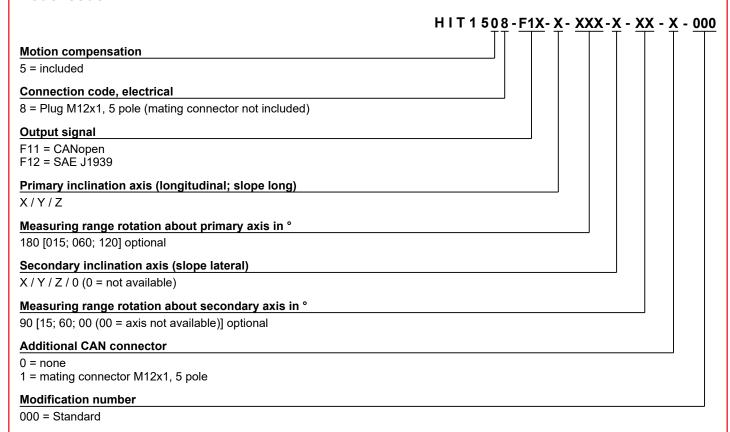


"right hand rule"

#### Pin connections

Plug M 12x1, 5 pole	Socket M12x1, 5 pole	Pin	Output signal: F1X	
			Signal	Description
1	5 1	1	CAN_SHLD	Shield/housing
5		2	CAN_V+	External supply +
24 1		3	CAN_GND	Ground / 0 V / V -
2 ( • )	10092	4	CAN_H	Bus line dominant high
3	3	5	CAN_L	Bus line dominant low

#### Model code



#### **Note**

The information in this brochure relates to the operating conditions and applications described. For applications or operating conditions not described, please

contact the relevant technical department.

Subject to technical modifications.

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