



Linear Position Transducer Flat Housing Design HLT 2500-F1

Description:

The sensor works on the principle of magnetostriction.

The measuring principle determines the position, distance and/or a velocity signal based on elapsed time.

Utilizing this non-contact and wear-free measuring system, HYDAC offers a flat housing version in aluminum.

The different output signals (analog/digital) facilitate the connection of all HYDAC ELECTRONIC GMBH measurement and control devices as well as connection to standard evaluation systems (e.g. also to PLC controls).

The HLT 2500-F1 is primarily used in stationary applications, especially when a semi-integrated solution in hydraulic cylinders is not possible.

Special features:

- Accuracy $\leq \pm 0.05\%$ FS B.F.S.L.
- Very robust housing
- High resistance to shock and vibration
- Excellent EMC characteristics
- Non-contact and wear-free
- Persuasive price / performance ratio

Technical data:

Input data	
Measuring ranges	50 .. 4000 mm
Measured variable	Distance, position, speed
Mechanical connection	Flat housing
Housing	Aluminum
Output data	
Signal output analog	Current: 4 .. 20 mA or 20 ... 4 mA Voltage: 0 .. 10 V or 10 .. 0 V
Signal output digital	Profibus, CANopen, Device Net, SSI, EtherCAT
Measuring accuracy	
Resolution	max. 0.005 mm, 16 bit
Non-linearity	± 0.1 mm to 1,500 mm ± 0.15 mm > 1,500 mm
Repeatability	≤ 0.005 mm - ≤ 0.05 mm (length-dependent)
Temperature coefficient	< 0.0024 % FS / °F (analog) < 0.0009 % FS / °F (digital)
Installation position and travel speed	
No restrictions	
Environmental conditions	
Operating temperature range	32 .. +158 °F
Relative humidity	98 %, non-condensing
Storage temperature range	-22 .. +185 °F, dry
Vibration resistance to DIN EN 60068-2-6 at 50 .. 2000 Hz	≤ 10 g
Shock resistance to DIN EN 60068-2-27	≤ 100 g / 11 ms / half sine
CE mark	EN 61000-6-1 / 2 / 3 / 4
EMC	
- Emitted interference	DIN EN 61000-6-3
- Interference resistance	DIN EN 61000-6-2
Housing / Protection class to IEC 60529	Aluminum / IP 65 ¹⁾
Other data	
Electrical connection	
- Analog	- Flying lead, length 1 m ¹⁾ - Male M16, 6 pole - Male M16, 8 pole
- CANopen, Device Net	Female M12x1, 5 pole + male M12x1, 5 pole
- Profibus	Female M12x1, 5 pole + male M12x1, 5 pole + male M8, 4 pole
- Synchronous Serial Interface	CONTACT male, 12 pole
- EtherCAT	2 female M12x1, 4 pole + male M8, 4 pole.
Supply voltage	24 V DC $\pm 10\%$
Current consumption without load	< 250 mA
Weight	Depends on length

Note: Reverse polarity protection of the supply voltage and excess voltage protection are provided.

FS (Full Scale) = relative to the complete measuring range

¹⁾ Other versions are possible.

Model code:

Stationary **HLT 2 5 0 0 - F1 - XXX - XXX - XXXX - 000**

Design/Geometry type

5 = Profile

Mechanical connection

F1 = Flat housing

Electrical connection

Signal output analog

K01 = Flying lead, length 1 m

M06 = Male M16, 6 pole

M08 = Male M16, 8 pole

Signal output CANopen, Device Net

C61 = Female M12x1, 5 pole + male M12x1, 5 pole

Signal output Profibus

P61 = Female M12x1, 5 pole + male M12x1, 5 pole
+ male M8, 4 pole

Signal output Synchronous Serial Interface

S01 = CONTACT male, 12 pole

Signal output EtherCAT

E51 = 2 female M12x1, 4 pole + male M8, 4 pole

Signal output

C01 = Analog 4 .. 20 mA, 3 conductor

C02 = Analog 20 .. 4 mA, 3 conductor

B01 = Analog 0 .. 10 V

B02 = Analog 10 .. 0 V

ETC = EtherCAT

SSI = Synchronous Serial Interface

CAN = CANopen

PRO = Profibus

DVN = Device Net

Measuring range in mm (50 to 4000 mm)

Example

0150 = 150 mm

Modification

000 = Standard

Items supplied:

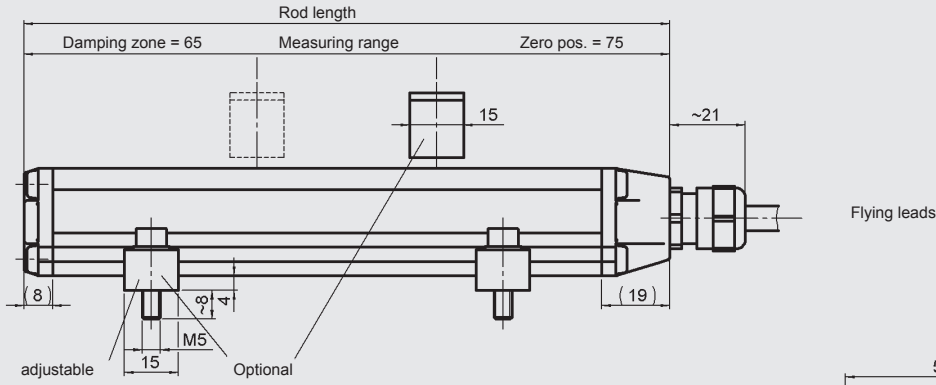
- HLT 2500-F1
- Installation instructions German/English
- HLT 2000 CD incl. case

Accessories:

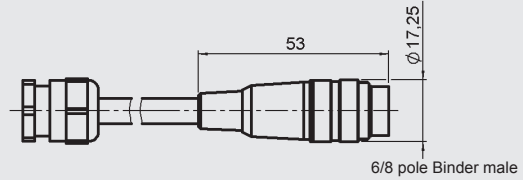
Appropriate accessories, such as position magnets, etc. can be found in the Accessories section of the Electronics brochure. The recommended position magnet ZBL MF 38-18, part no. 6084456, must be ordered separately.

Dimensions:

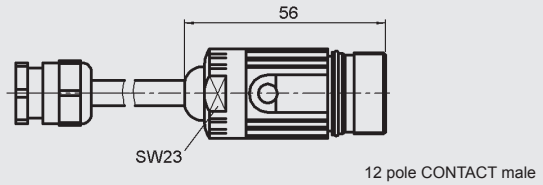
Signal output: analog (K01)



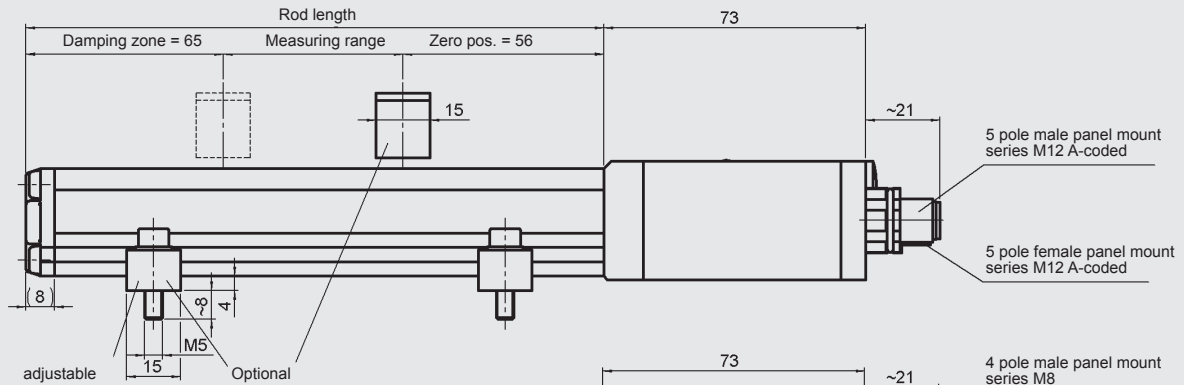
Signal output: analog (M06, M08)



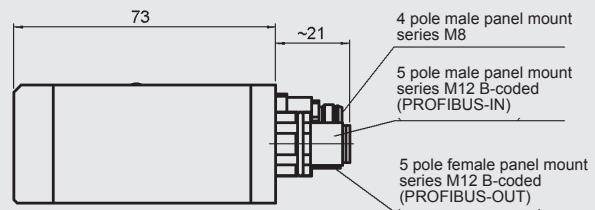
Signal output: Synchronous Serial Interface (S01):



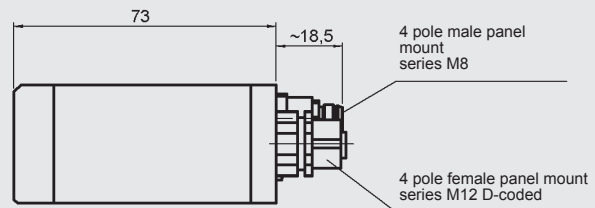
Signal output: CANopen Device Net (C61)



Signal output: Profibus (P61)



Signal output: EtherCAT (E51)



Note:

The information in this brochure relates to the operating conditions and applications described. For applications and operating conditions not described, please contact the relevant technical department. Subject to technical modifications.

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